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A REVERSE TO THE JEFFREYS-LINDLEY PARADOX*

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Abstract. In this paper the seminal Jeffreys–Lindley paradox is regarded from a mathematical point of view. We show that in certain scenarios the paradox may emerge in a reverse direction.

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1. INTRODUCTION

The Jeffreys–Lindley paradox (see [2], [6], [9]) describes a discordance between frequentist and Bayesian hypothesis testing. When comparing a simple null hypothesis against a diffuse alternative, it has been found that a given sample may simultaneously lead to a frequentist rejection of the null hypothesis (because the *p*-value is smaller than a critical alpha) and a Bayesian support for the null hypothesis (because the value of the Bayes factor exceeds some critical threshold). The 'paradox' has been the subject of intensive debate in the statistical literature and this debate is still ongoing ([6], [10], [11]).

The classical example used to illustrate the discordance involves Gaussian populations with known variance and a point null hypothesis for the mean versus a diffuse alternative hypothesis. In words, the argument usually goes as follows: A value for the test statistic is chosen that gives a small but constant *p*-value with increasing sample size (hence the test value scales with the sample size), thus leading to a systematic rejection of the null hypothesis in frequentist statistics. Under the same scenario, it can then be shown that, with increasing sample sizes, the Bayes factor of the alternative hypothesis over the null goes to zero. Thus, asymptotically, the Bayesian will favour the null hypothesis. The same phenomenon can be

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observed with several non-Gaussian populations. In this paper we show, however, that there also exist scenarios in which the Jeffreys–Lindley paradox may appear in a reversed way. That is to say, we show that it may occur that the frequentist asymptotically maintains the null hypothesis whereas the Bayesian rejects it.

2. THE JEFFREYS-LINDLEY PARADOX REVERSED

We will construct an example where the Jeffreys–Lindley paradox appears in a reversed way. As a first step, we define an auxiliary function $f : \mathbb{R} \to [0, +\infty)$ as follows:

(2.1)
$$f(x) = \begin{cases} \frac{A}{|x|} \exp\left\{-\frac{\log(1/|x|)}{\log\left(\log(1/|x|)\right)}\right\} & \text{if } 0 < |x| < \frac{1}{e^2}, \\ 0 & \text{elsewhere.} \end{cases}$$

The constant A in the above formula is chosen in such a way that the function f integrates to one. Thus f can be considered a probability density in the strict sense of the word. This density has the following properties:

- *f* is symmetric around the origin.
- *f* is piecewise continuous.
- f has compact support and thus has moments of all orders.

• Due to a singularity at x = 0, all convolution powers f^{*n} are unbounded. A proof of the last property can be found in [4]. In the following, the variance of f will be denoted by σ^2 . A family $\{f(\bullet | \theta) | \theta \in \mathbb{R}\}$ of densities is defined as

(2.2)
$$f(x \mid \theta) = f(x - \theta).$$

Suppose now that a population is given with a probability density $f(\bullet | \theta)$, where the parameter θ , presenting the population mean, is unknown. In the following two subsections we will compare the Bayesian and frequentist approach when testing the null hypothesis $H_0: \theta = 0$ against the alternative hypothesis $H_1: \theta \neq 0$. To this end, in both scenarios, a sample X_1, X_2, \ldots, X_n is drawn from the population, and the sample mean Y_n , defined as

(2.3)
$$Y_n = \frac{X_1 + X_2 + \ldots + X_n}{n},$$

is chosen to be the test statistic.

2.1. The Bayesian approach. In a Bayesian framework of hypothesis testing we need to specify priors for the null and the alternative hypothesis. In our example the null prior is chosen to be the Dirac measure δ_0 in $\theta = 0$. In order to reverse the Jeffreys–Lindley paradox, the alternative prior p is constructed as follows. First we define a sequence I_1, I_2, I_3, \ldots of subsets of \mathbb{R} by

$$I_n = \left\{ \theta \in \mathbb{R} \mid f^{*n}(\sigma\sqrt{n} - n\theta) \ge n2^n f^{*n}(\sigma\sqrt{n}) \right\}.$$

Now, on the one hand, the functions f^{*n} being unbounded and piecewise continuous, the subsets I_n must have non-empty interior, and therefore must be of strictly positive Lebesgue measure. On the other hand, the f^{*n} being integrable, the subsets I_n must be of bounded Lebesgue measure. Altogether one may talk about the uniform distribution on I_n and about its density p_n . In terms of these p_n , we define the prior p as

(2.4)
$$p(\theta) = \sum_{k=1}^{\infty} 2^{-k} p_k(\theta).$$

From Lebesgue's convergence theorems (see, for example, [3], [7], [8]) it follows that p is a well-defined density with total probability mass equal to one. With the likelihood given by (2.2) the hypotheses to be tested are

$$H_0$$
: prior is δ_0 against H_1 : prior is p .

Bayesians will base their decision on the Bayes factor, which is in this scenario, for an arbitrary outcome y of Y_n , given by

(2.5)
$$\operatorname{BF}_{n}(y) = \frac{\int\limits_{-\infty}^{+\infty} f_{Y_{n}}(y \mid \theta) p(\theta) \,\mathrm{d}\theta}{f_{Y_{n}}(y \mid 0)}$$

In the above formula, $f_{Y_n}(\bullet | \theta)$ stands for the probability density of the variable Y_n , given θ . If this Bayes factor exceeds some prescribed threshold, then the Bayesian rejects the hypothesis H_0 . Suppose now that we observe the outcome

$$y_n = \frac{\sigma}{\sqrt{n}}$$

for the sample mean Y_n . The value of the density f_{Y_n} in y_n may be expressed (see [3], [5]) in terms of a convolution power of f as

$$f_{Y_n}(y_n \mid \theta) = n f^{*n}(\sigma \sqrt{n} - n\theta).$$

Using this in (2.5), one arrives at

$$\begin{split} \mathbf{BF}_n(y_n) &= \int_{-\infty}^{+\infty} \frac{f_{Y_n}(y_n \mid \theta)}{f_{Y_n}(y_n \mid 0)} \, p(\theta) \, \mathrm{d}\theta = \int_{-\infty}^{+\infty} \frac{f^{*n}(\sigma\sqrt{n} - n\theta)}{f^{*n}(\sigma\sqrt{n})} \, p(\theta) \, \mathrm{d}\theta \\ &= \sum_{k=1}^{\infty} \int_{I_k} \frac{f^{*n}(\sigma\sqrt{n} - n\theta)}{f^{*n}(\sigma\sqrt{n})} \, 2^{-k} p_k(\theta) \, \mathrm{d}\theta \\ &\geqslant \int_{I_n} \frac{f^{*n}(\sigma\sqrt{n} - n\theta)}{f^{*n}(\sigma\sqrt{n})} \, 2^{-n} p_n(\theta) \, \mathrm{d}\theta \\ &\geqslant \int_{I_n} n 2^n \, 2^{-n} p_n(\theta) \, \mathrm{d}\theta = n. \end{split}$$

It thus appears that

(2.6)
$$\lim_{n \to \infty} \mathrm{BF}_n(y_n) = \infty$$

Thus, asymptotically, the Bayesian will reject H_0 when confronted with outcomes y_n of the sample mean Y_n .

2.2. The frequentist approach. The frequentist approach is based on the *p*-value. If this *p*-value is below some prescribed threshold (typically 0.05), then the frequentist will reject the hypothesis H_0 . The *p*-value is computed starting from the null-hypothesized value for θ , in our scenario the value $\theta = 0$. Contrary to the Bayesian approach, the form of the alternative hypothesis H_1 does not play an essential role in the frequentist decision procedure. When testing in a two-sided way, the *p*-value in our particular scenario, given the outcome $y_n = \sigma/\sqrt{n}$ for the sample mean Y_n , would be determined as

(2.7)
$$PV_n = 2 \times \{1 - F_{Y_n}(y_n \mid H_0)\},\$$

where $F_{Y_n}(\bullet | H_0)$ stands for the cumulative distribution function of Y_n under H_0 . In order to evaluate the *p*-value asymptotically, we define the variable Z_n as

$$Z_n = \frac{Y_n}{\sigma/\sqrt{n}}.$$

Note that Z_n is under H_0 precisely the standardization of Y_n . Given the outcome y_n for the sample mean Y_n one may rewrite (2.7) as follows in terms of the Z_n :

$$PV_n = 2 \times \{1 - F_{Z_n}(1 \mid H_0)\}.$$

The second moment of the population being finite, the classical central limit theorem may be applied. Thus, denoting the cumulative distribution function of the standard Gaussian distribution by Φ , the asymptotic *p*-value turns out to be

(2.8)
$$\lim_{n \to \infty} PV_n = 2 \times \{1 - \Phi(1)\} = 0.32.$$

When observing a *p*-value of this size the frequentist will generally decide not to reject H_0 . Hence, asymptotically, the frequentist will maintain H_0 when confronted with an outcome y_n of the sample mean Y_n .

3. CLOSING REMARKS

We have constructed an example in which the Bayesian (basing his decision on (2.6)) will asymptotically reject H_0 whereas the frequentist (basing his decision on (2.8)) will asymptotically *not* reject this hypothesis. It thus appears that, in the absence of sufficient regularity of likelihood or prior, the Jeffreys–Lindley paradox

may manifest itself in a reversed way. It should be noted that, rather than the specific function f defined by (2.1), any persistently unbounded probability density (see [4]) will lead to a reversion of the paradox.

In the likelihood defined by (2.2), the parameter θ presents the population mean. For this reason, at first sight, it may seem natural to use its empirical counterpart, the sample mean Y_n defined by (2.3), as the test statistic. However, in the proposed scenario, the sample mean fails to be a sufficient estimator for the parameter θ . Future work needs to be done to construct an example in which the paradox is reversed through a sufficient test statistic.

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